

MPS Models Can Tell you Where to Drill

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Content of Presentation

- MPS – A quick overview
- The workflow of the Methodology
- Some Definitions – Gaussian Kernel, Convolutions, Entropy
- The MPS workflow in GeoScene3D
- The Study Area and Data
- Results
- Conclusions

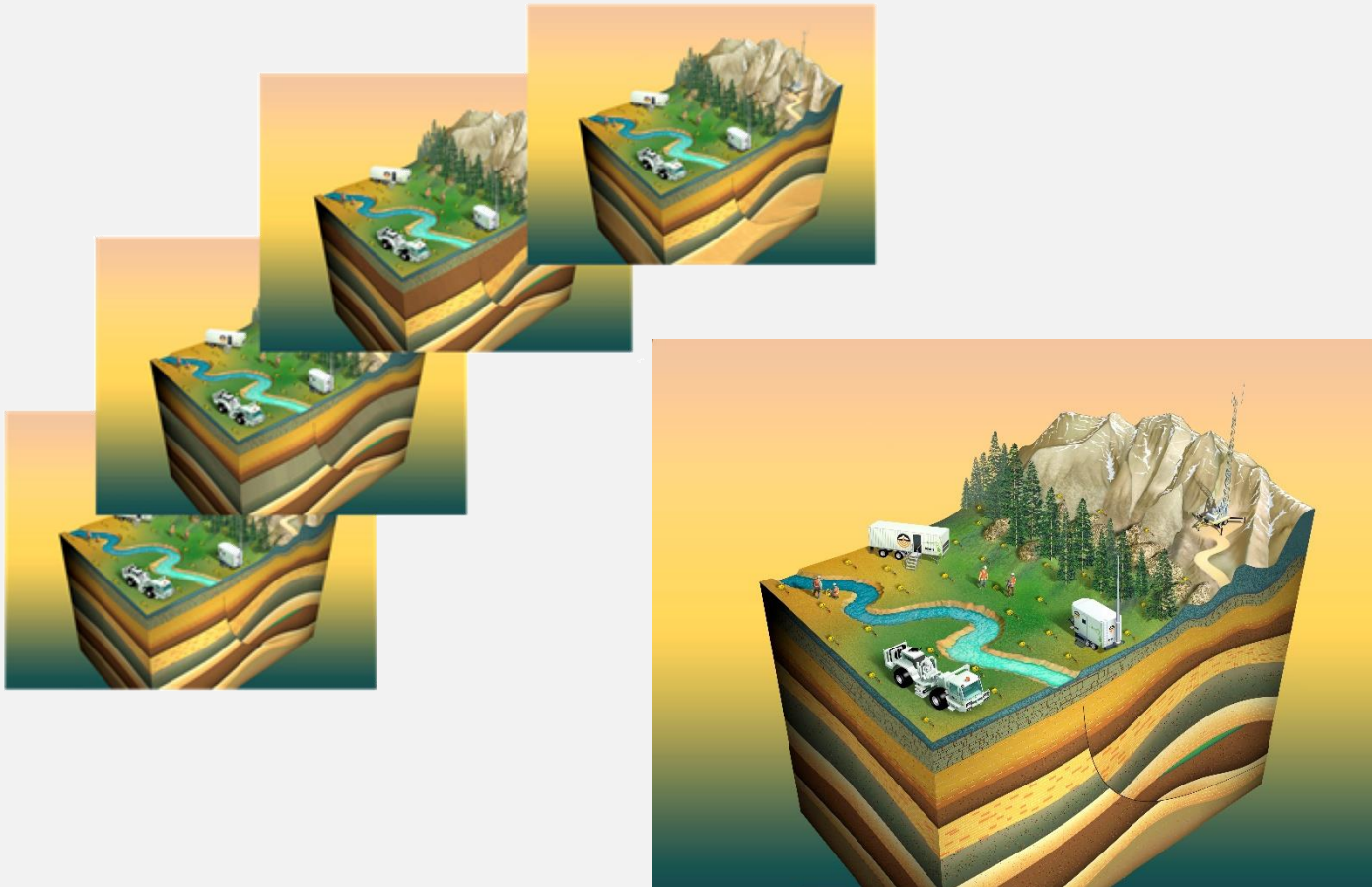
Motivation

- Developed a MPS tool in GeoScene3D
- Part of the GAP Project
- How to utilize MPS – realizations?

Workflow:

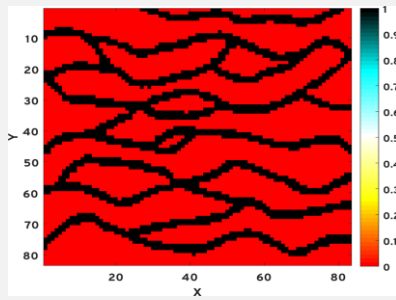


The Fundamental Problem

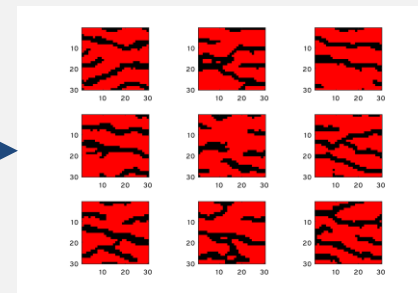


Multiple Point Statistics (MPS)

$$f_I(\bar{m}) \propto \prod_i f_{I_i}(\bar{m}) \propto f_{I_{TI}}(\bar{m}) f_{I_{hard}}(\bar{m}) f_{I_{soft}}(\bar{m})$$

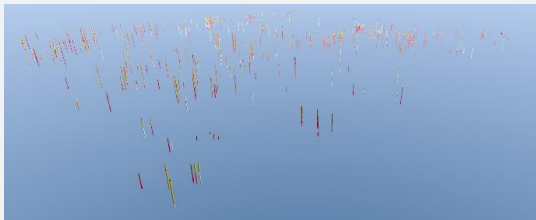


MPS Algorithm

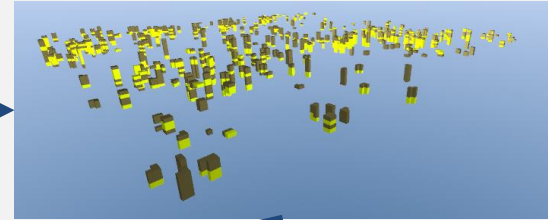


Realizations from $f_{I_{TI}}(\bar{m})$

Borehole Data

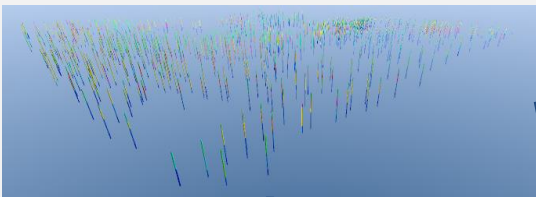


Categorize and make Hard data Grid

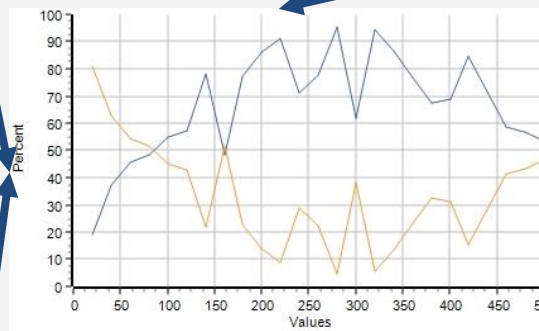
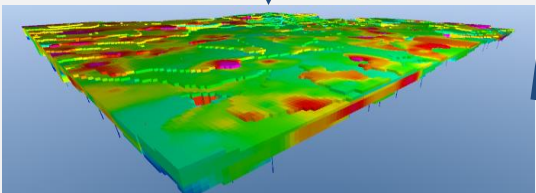


FP_C2 - Sand
FG_C1 - Clay

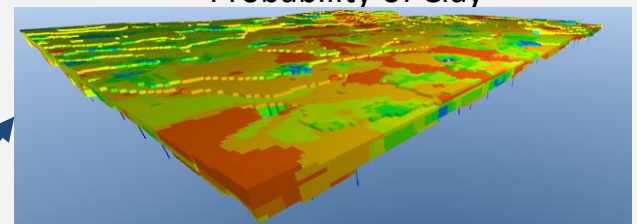
Resistivity data



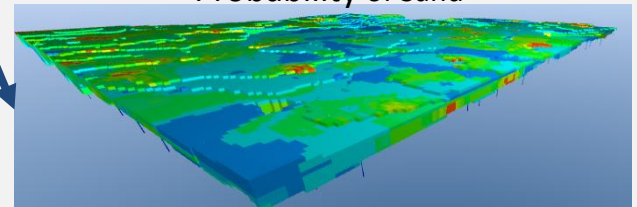
3D interpolation



Probability of Clay



Probability of Sand



Workflow of the Method

Run MPS
Simulations

Compute the
Entropy

Convolve with a
Gaussian Kernel

Find Maximum
Entropy

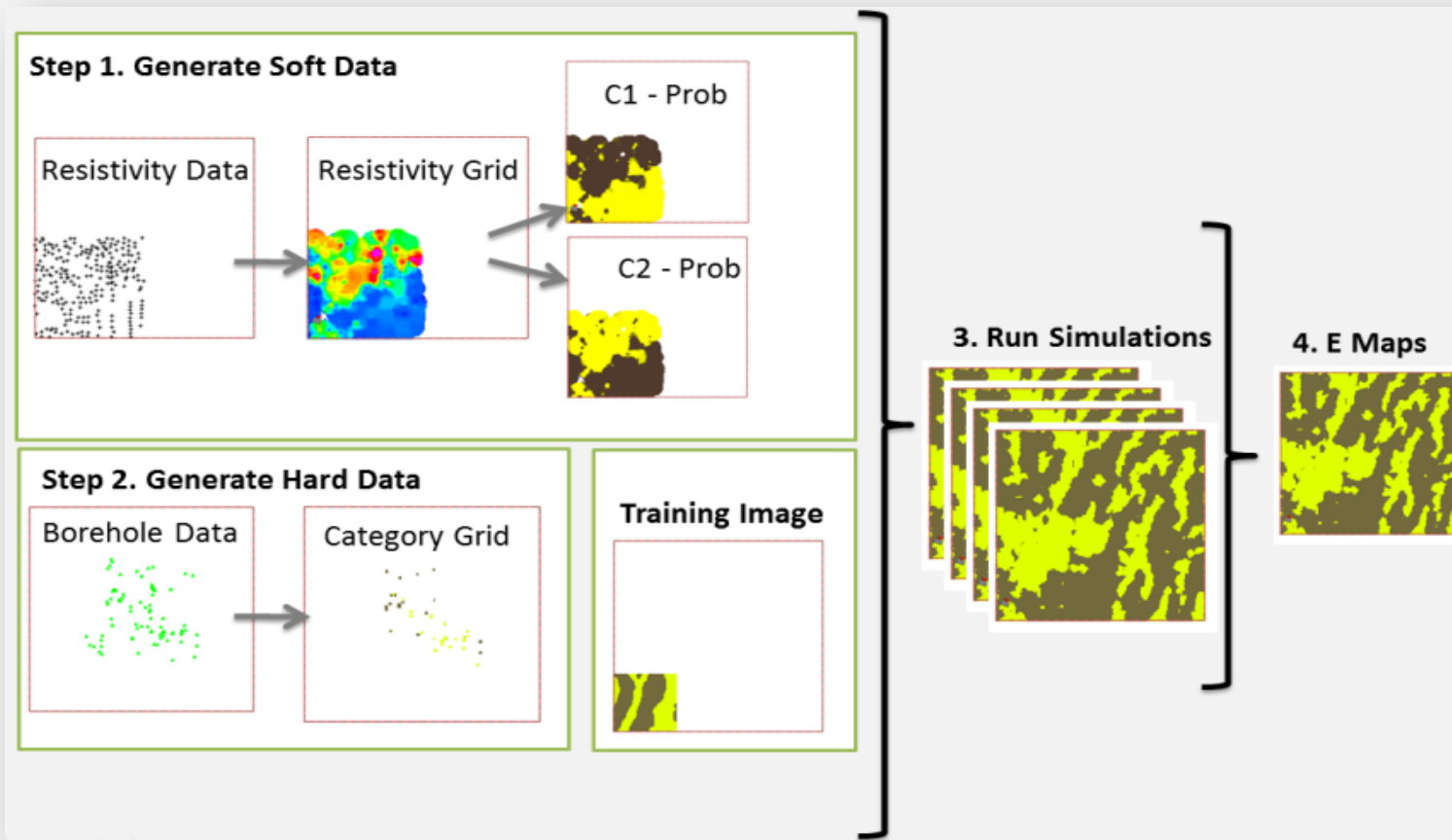
MPS Workflow in GeoScene3D

Make a Training
Image

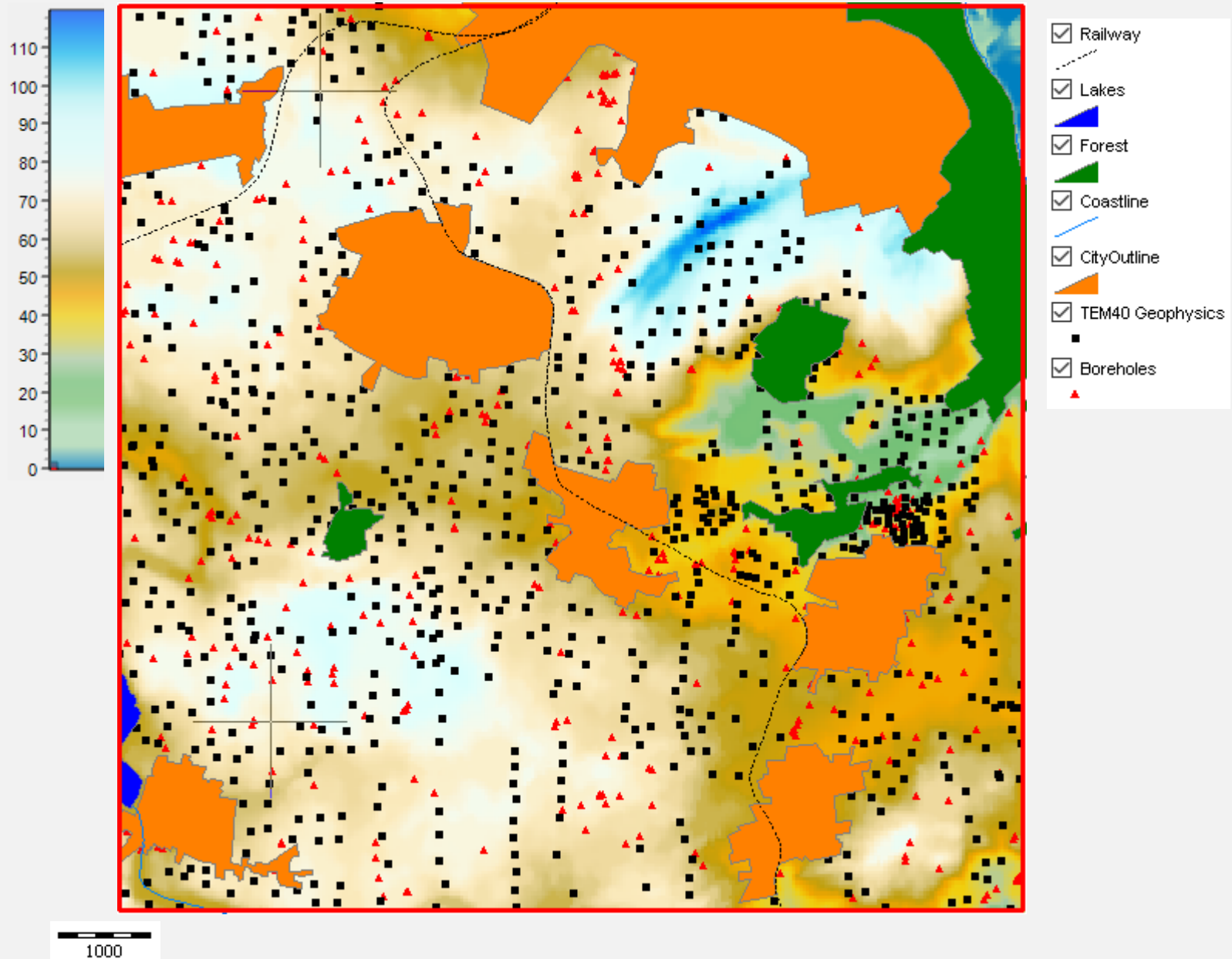
Define Hard/Soft
Data

Run Simulations

Alternatively
compute E-Maps



The Simulation Area

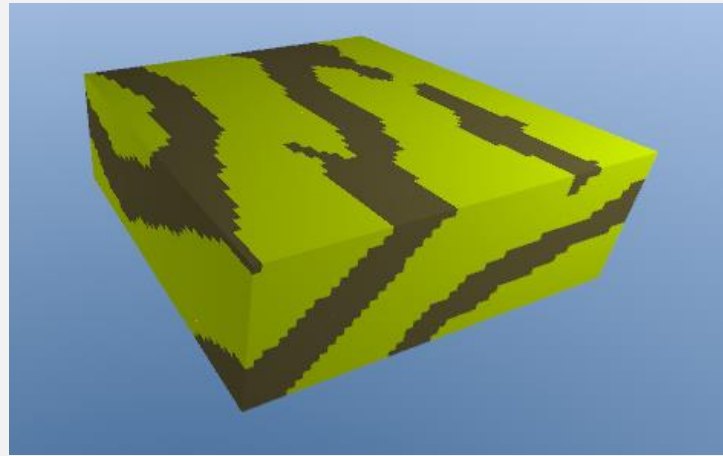


The Training Image (TI)

Horizontal slices

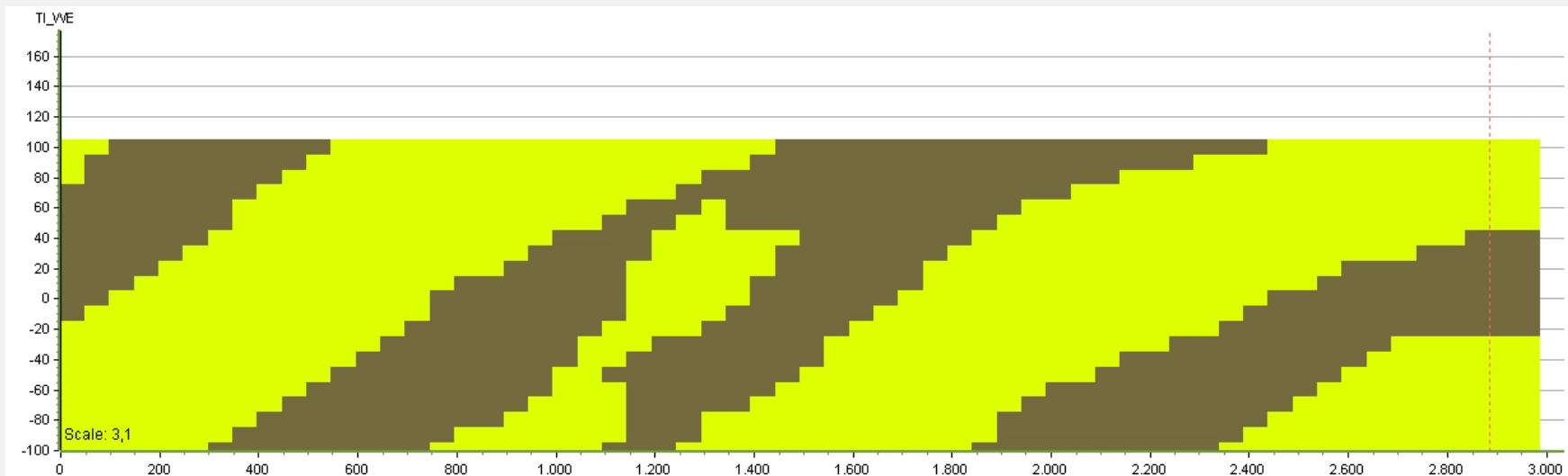


3D View



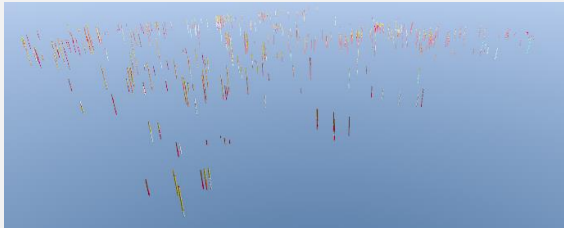
- 3D Grid: 61x61x21 Voxels
- Total # Voxels: 78141
- Voxel Size: 50x50x10 m

WE cross-section

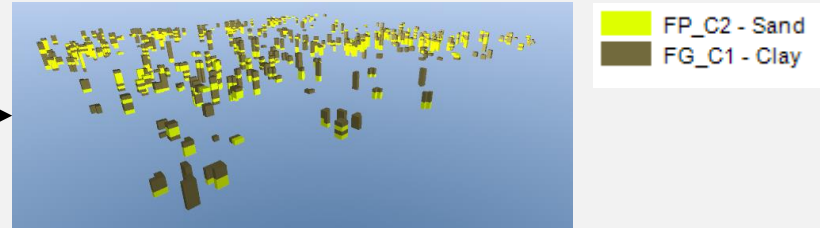


Hard and Soft data

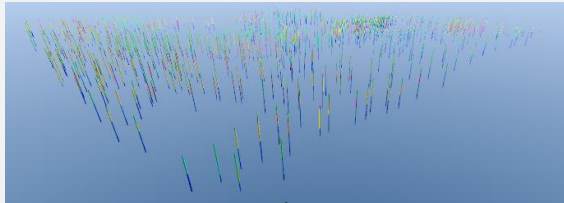
Borehole Data



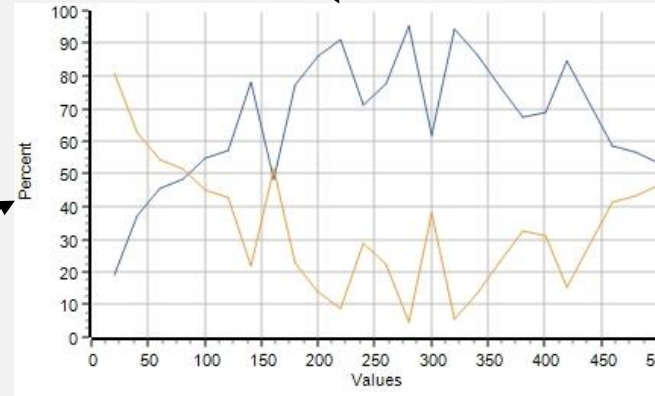
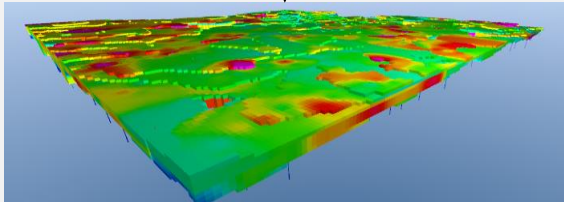
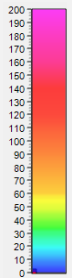
Categorize and make
Hard data Grid



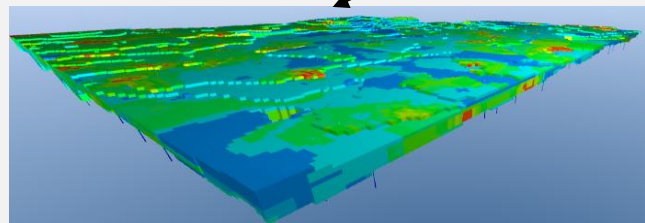
Resistivity data



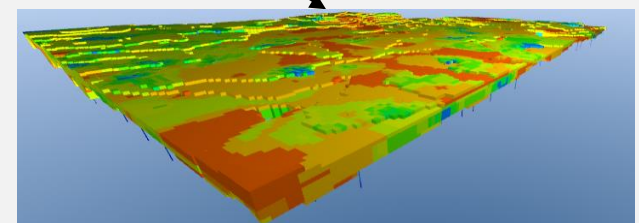
3D interpolation



Probability of Sand





Probability of Clay



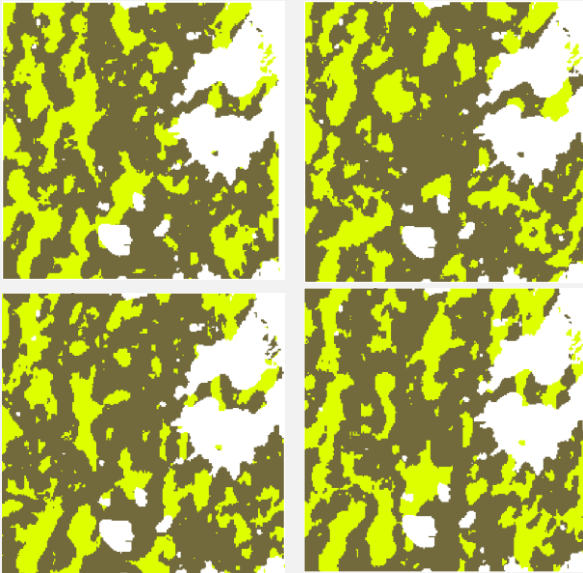
Simulation Results

Simulation Setup:

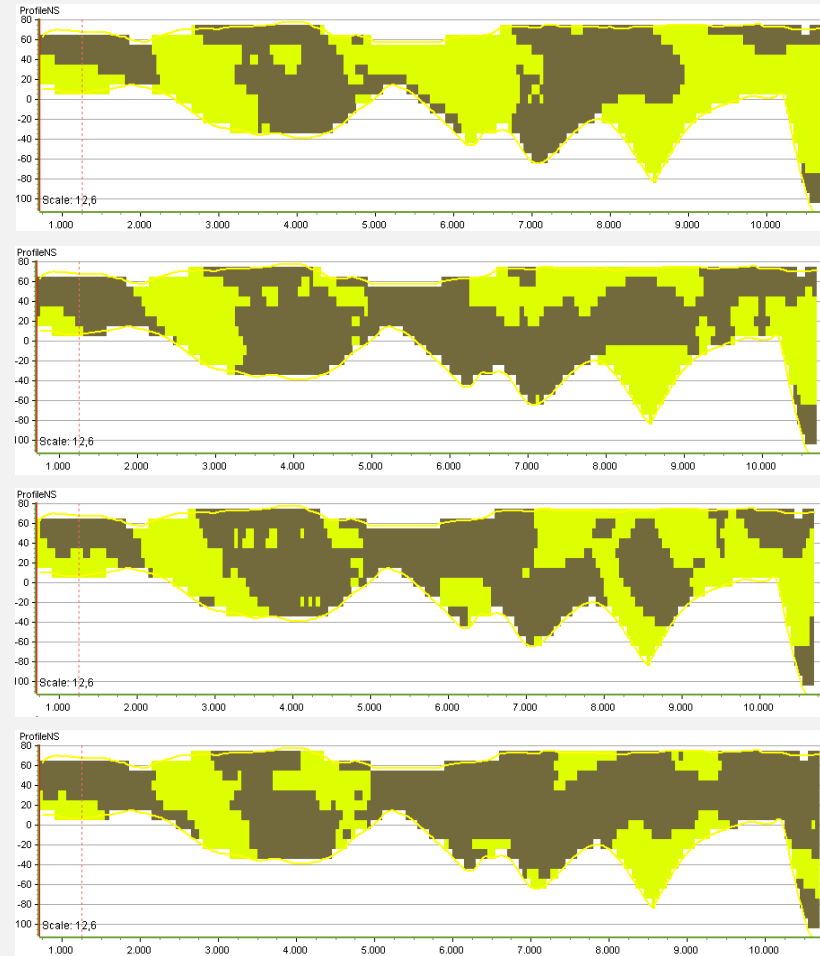
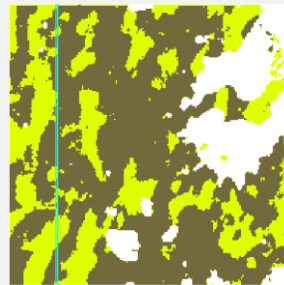
- The Snesim Algorithm
- Template Size: 5-5-3
- 5 Multiple Grids
- Random Simulation path

 FP_C2 - Sand
 FG_C1 - Clay

4 realizations



The Mode Model

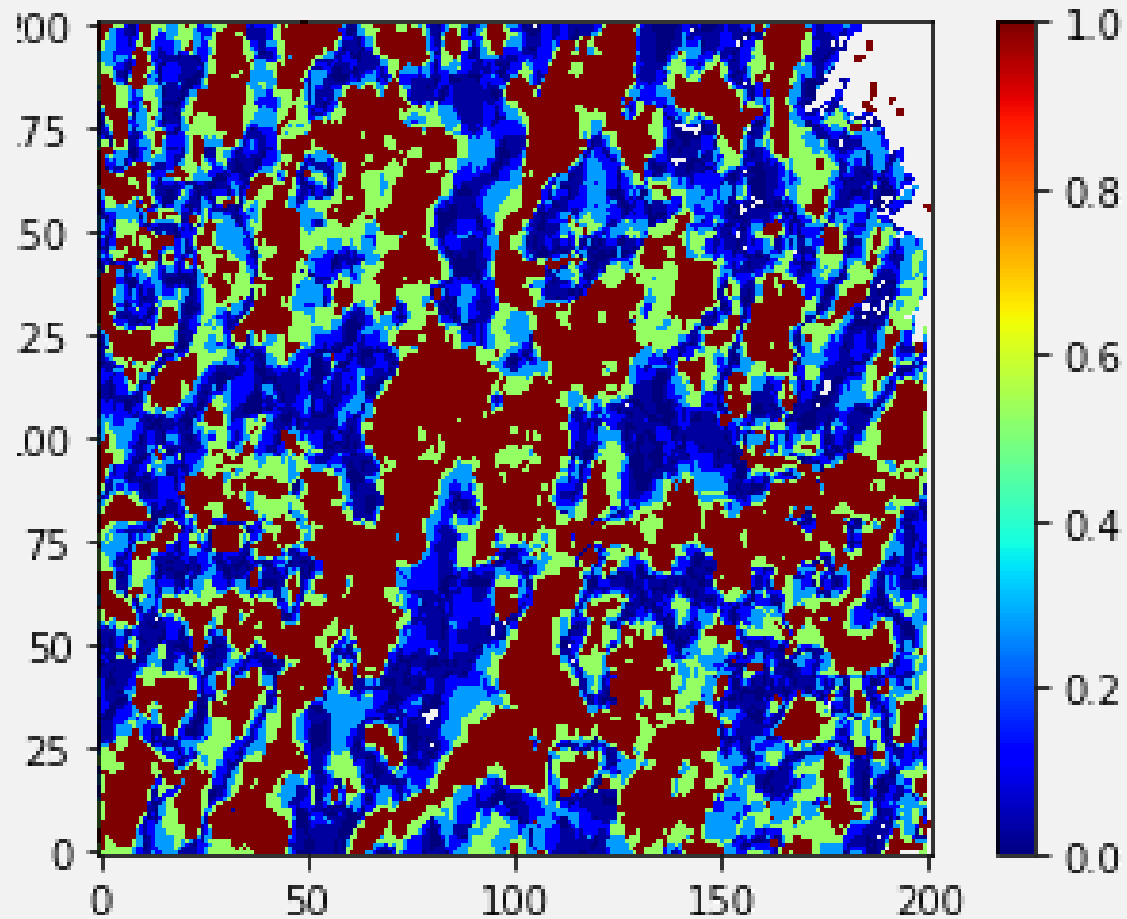


The Shannon Entropy from Information Theory:

$$S = - \sum_i (P_i \log_2 P_i)$$

- S is proportional to uncertainty
 - S = 1 indicates max uncertainty – No information
 - S = 0 indicates no uncertainty – Fully informed.
-
- Equal number of outcomes for all categories in a pixel/voxel from a simulation result in S=1
 - All outcomes in pixels/voxel has the same category: S=0

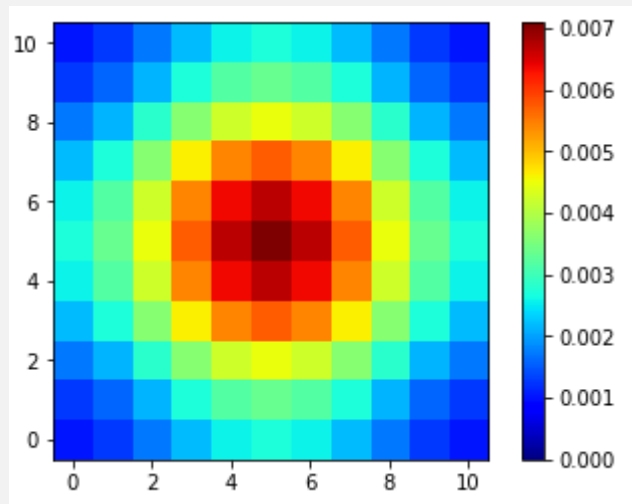
Entropy Grid with no convolution



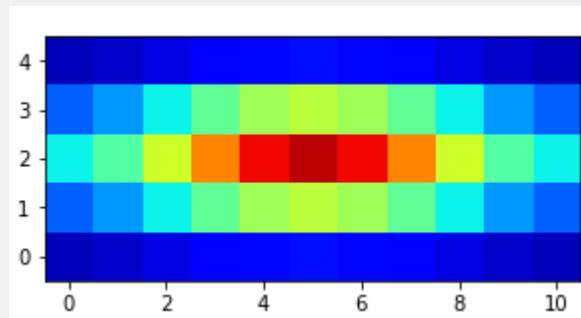
Smoothed Dirac Delta in 3D.

3D Gaussian Kernel with ellipsoidal shape of 11*11*5 cells. 500m x 500m x 50m
Std. of 3, 3 and 1

Horizontal slize

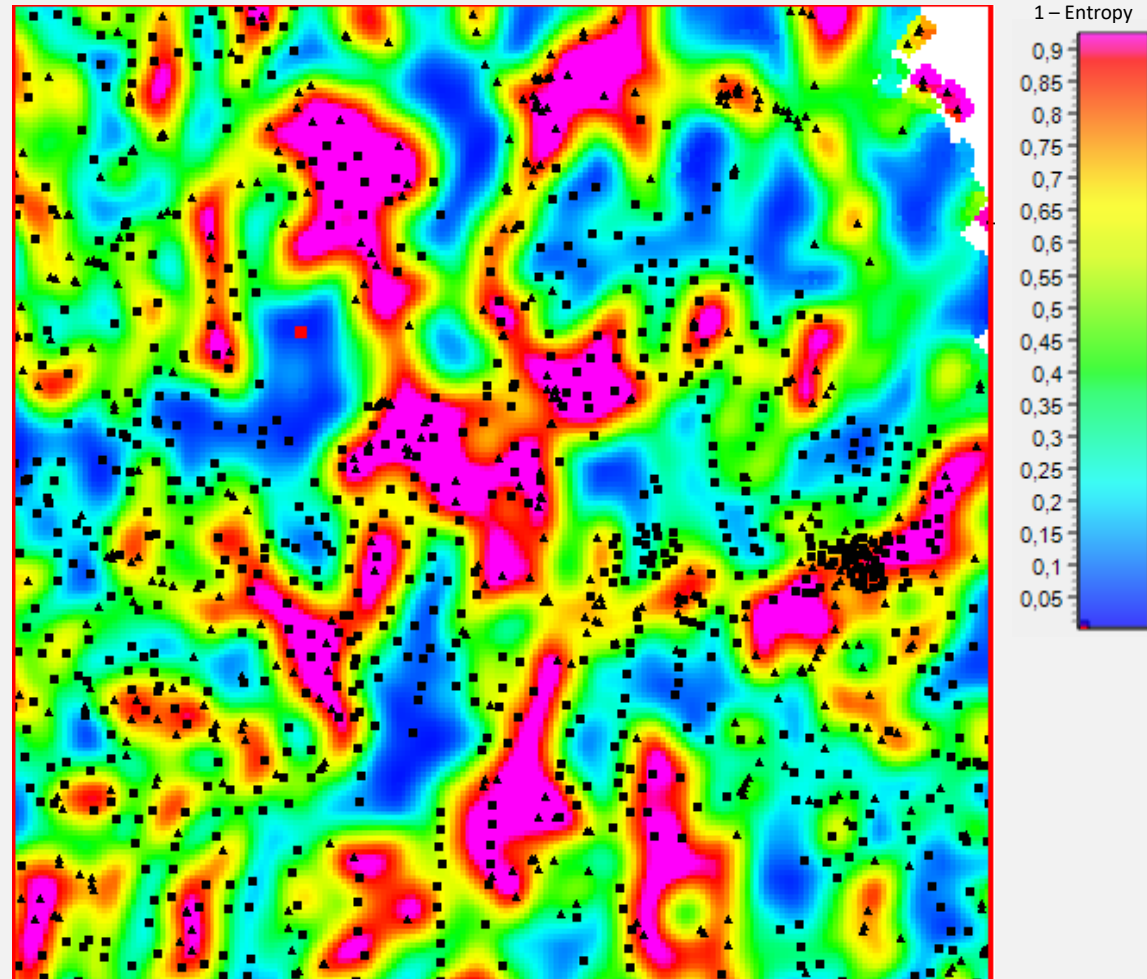


Verticle Slize



1 – Entropy in the upper 10 meters.

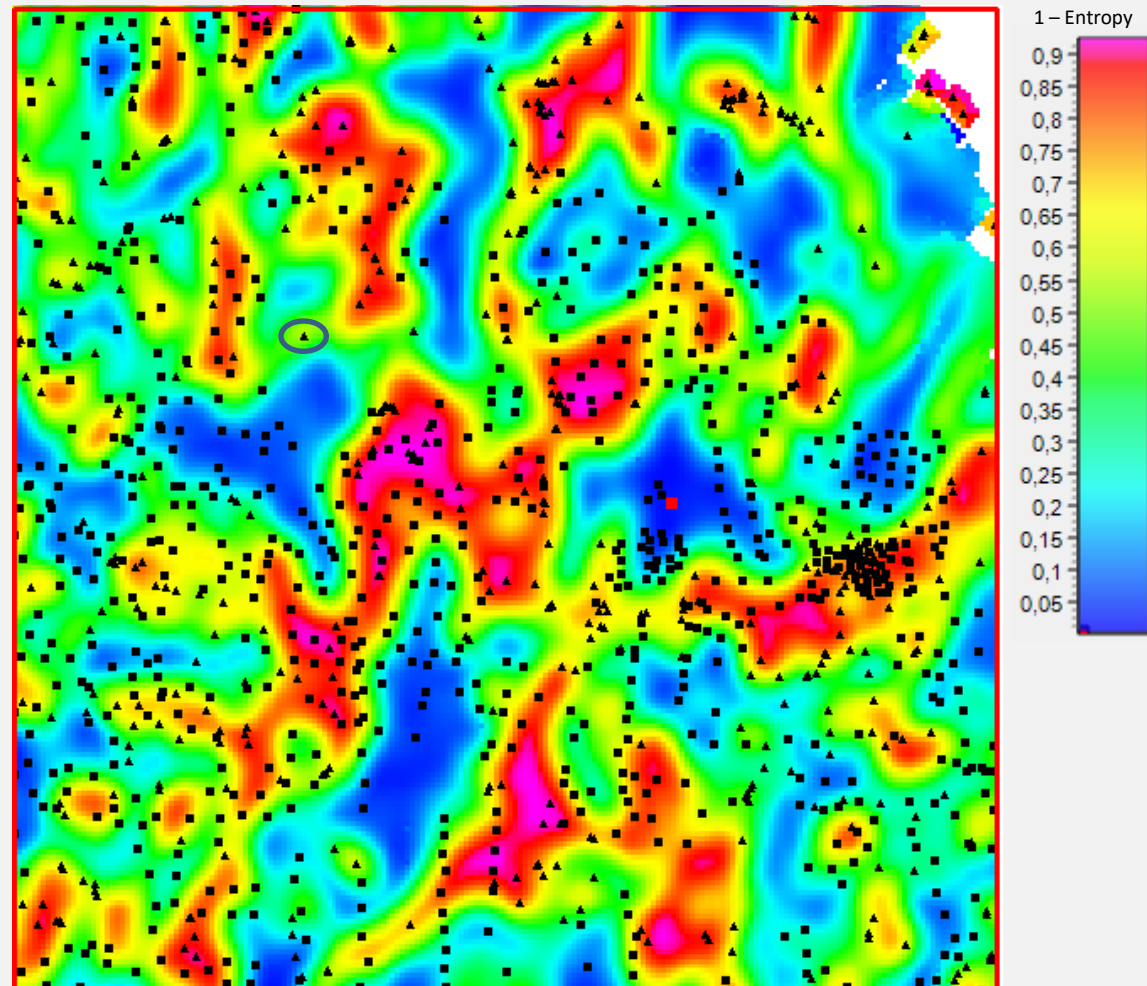
- ▲ Wells
- TEM
- WHU



$$WHU = \frac{1}{n} \sum_n (1 - S(n))$$

1 – Entropy in the upper 10 meters.

- ▲ Wells
- TEM
- WHU



$$WHU = \frac{1}{n} \sum_n (1 - S(n))$$

Concluding remarks

- MPS Realizations represent different Geologic scenarios
- The Entropy provides information on the certainty/quality of our probabilistic model
- Convolving the Entropy model allows including the surrounding information content
- Obtaining information (e.g. by drilling) at the location with highest entropy will update the probabilistic model the most
- Necessary to apply a Gaussian Filter, or is the spatial information already represented in the MPS realizations?